

The company under the name JSC "Precizika Metrology" began work after the change of name of the Lithuanian - American Joint Venture "Brown \& Sharpe - Precizizk". The company has a proud history of old traditions in the leadership of design and production of metrological equipment. Its workforce has been involved for over fifty years in the supply of measuring technology and systems to automate factories as well as in the development of optical scale manufacturing technology.
In 2000, the production process was certified to fully meeting the requirements of EN ISO 9002:1994, in 2003 - EN ISO 9001:2000
The company's goal is to consistently supply high quality products and services to meet customer demands on a timely basis. The company's main products are linear and angular glass scale gratings, and the linear and rotary displacement measuring systems.
JSC "Precizika Metrology" represents worldwide known companies and suppliers of measuring equipment, CNC centers, executes installation and services of them, trains the users, and executes upgrading of used CMM and manual cutting machine-tools.

## A58H1 <br> PHOTOELECTRIC ROTARY ENCODER

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The encoder A58H1 is used to measure angular position of the key machine components, industrial robots, comparators, rotary tables,
servo drives and to establish an informational link with DCC, NC or Digital Readout Units. The encoder has external flexible coupling. The encoder is used in automatic control, on-line gauging, process monitoring systems, etc. Three versions of output signals are available:

- A58H1-A - sinusoidal signals, with amplitude approx. $11 \mu \mathrm{App}$;

A58H1-AV - sinusoidal signals, with amplitude approx. 1 Vpp
A58H1-F - square-wave signals (TTL) with integrated subdividing electronics for interpolation $\mathrm{x} 1, \mathrm{x} 2, \times 3, \times 4, \times 5, \times 8, \times 10$.

## A58H1

## RECOMMENDED APPLIGATIONS

## 管 

## MECHANIGAL DATA

| Line number on disc (z) | 100 ;250; 500; 600; 800; 1000; 1024; 1125; 1250; 1500; 2000; 2500; 3000; 3600; 4000; 5000; 9000; 10800 | Rotor moment of inertia | $<1.5 \times 10^{-4} \mathrm{kgm}^{2}$ |
| :---: | :---: | :---: | :---: |
|  |  | Protection (housing) (IEC 529) | IP64 |
|  |  | Protection (shatt side) ( IEC 529) | \|P64 |
|  |  | Maximum weight without cable | 0.3 kg |
| Pulse number per shaft revolution for A58H1-F | Zxk, where <br> $\mathrm{k}=1,2,3,4,5,8,10$ | Operating temperature | $-10 . . .+70{ }^{\circ} \mathrm{C}$ |
| Maximum shaft speed | 10000 rpm | Storage temperature | $-30 . . .880$ |
| Permissible motion of shaft: <br> - axial <br> - radial (at shaft end) | $\begin{aligned} & \pm 0.03 \mathrm{~mm} \\ & 0.05 \mathrm{~mm} \end{aligned}$ | Maximum humidity (non-condensing) | $98 \%$ |
|  |  | Permissible vibration ( 55 to 2000 Hz ) | $\leq 100 \mathrm{~m} / \mathrm{s}^{2}$ |
| Accuracy ( $T_{1}$-period of ines on disc in arc. sec) | $\pm 0.17$, arc. sec | Permissible shock (11 ms) | $\leq 300 \mathrm{~m} / \mathrm{s}^{2}$ |
| Starting torque at $20^{\circ} \mathrm{C}$ | $\leq 0.025 \mathrm{Nm}$ |  |  |



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## ELECTRICAL DATA

| VERSION | A58H1-A $\sim 11$ AApp | A58H1-AV ${ }^{\text {1 }} 1 \mathrm{Vpp}$ |  |
| :---: | :---: | :---: | :---: |
| Supply voltage ( $U_{P}$ ) | $+5 \mathrm{~V} \pm 5 \%$ | +5V $\pm 5 \%$ | $+5 \mathrm{~V} \pm 5 \%$; (10 to 30) V |
| Max. supply curent (without load) | 80 mA | 120 mA | 120 mA |
| Light source | LED | LED | LED |
| Incremental signals | Two sinusiolal I , and I Amplitude at 1 k K2 load $-11=7-16 \mu A$ $-12=7-16 \mu A$ | Differential sine $+\mathrm{A} /-\mathrm{A}$ and $+\mathrm{B} /-\mathrm{B}$ Amplitude at $120 \Omega$ load. $\begin{aligned} -A & =0.6-1.2 \mathrm{~V} \\ -B & =0.6-1.2 \mathrm{~V} \end{aligned}$ | Differential square-wave U1/ $\sqrt{1}$ and $\mathrm{U} 2 \sqrt{\sqrt{2} 2}$. <br>  <br>  |
| Reference signal | One quasi-triangular 1 peak per revolution. Signal magnitude at 1 k $\Omega$ load: $I_{0}=2-8 \mu \mathrm{~A}$ (usable component) | One quasi-triangular $+R$ and its complementary $-R$ per revolution. Signals <br>  <br> $\mathrm{R}=0.2-0.8 \mathrm{~V}$ (usable component) | One differential square-wave UO/UO per revo <br> Iution. Signal levels at 20 mA load current: <br> low (logic " $O$ ") $<0.5 \mathrm{~V}$ at $U_{P}=+5 \mathrm{~V}$ <br> high (logic " 1 ") $>2.4 \mathrm{~V}$ at $\mathrm{U}_{\mathrm{P}}=+5 \mathrm{~V}$ <br> - high (logic "1") $>\left(U_{p}-2\right)$ V at $U_{p}=10$ to 30 V |
| Maximum operating frequency | $(-3 \mathrm{~dB}) \geq 160 \mathrm{kHz}$ | $(-3 \mathrm{~dB}) \geq 180 \mathrm{kHz}$ | $(160 \times k) k$ Hz, k-interpoation factor |
| Direction of signals | 1, lags 1, for clockwise rotation (viewed from shaft side) | +B lags +A for clockwise rotation (viewed from shaft side) | U2 lags U1 with clockwise rotation (viewed from shatt side) |
| Maximum rise and fall time | - | - | $<0.5$ н |
| Standard cable length | 1 m , without connector | 1 m , without connector | 1 m , without connector |
| Maximum cable length | 5 m | 25 m | 25 m |
| Output signals |  |  |  |

1. Maximum working rotation speed (with proper encoder counting) is linited by maximum operating frequency and maximum mechanica rotation speed.

If cable extension is used, power supply conductor cross--section should not be smaller than $0.5 \mathrm{~mm}^{2}$.

## MOUNTING REQUIREMENTS



## ACCESSORIES

| CONNECTORS FOR CABLE | B12 <br> 12-pin round connector | C9 <br> 12-pin round connector | C12 <br> 12-pin round connector | D9 <br> 9-pin flat connector | D15 <br> 15-pin flat connector | RS10 10-pin round connector | onc <br> 10-pin round connector |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| digital readout devices | CS3000 |  |  |  | CS5500 |  |  |
| EXtERNAL INTERPOLATOR | NK |  |  |  |  |  |  |

## ORDER FORM

| OUTPUT SIGNAL VERSION: | PULSE NUMBER PER REVOLUTION: | SHAFT HOLE DIAMETER: | SUPPLY VOLTAGE: | cable length: | CONNECTOR TYPE: |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & A \\ & A \\ & A \end{aligned}$ | $\begin{aligned} & 100 \\ & 100800 \end{aligned}$ | . 8, 10, 12, 14* mm |  <br> onn for A58HPF with HTL <br> outpur |  | W - without connecto B12 - round, 12 pinsC9 -round, 9 pins C12 - round, 12 pinsD9 - flat, 9 pins D9 - flat, 9 pinsD15 - flat, 15 pin RS10 - round, 10 pinsONC - round, 10 pins |
|  |  | *with additional hub for fixation from fang one side ation from flange side |  |  |  |

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[^0]:    D, mm

    | $\varnothing 6$ | $\varnothing 8$ | $\varnothing 10$ | $\varnothing 12$ | $\varnothing 14^{*}$ (on option) |
    | :--- | :--- | :--- | :--- | :--- | :--- |

    For one side fixation from encoder flange side

